

Derivation of Tables 3 through 5 in Okada (1992)

[I] Derivation of Table 3 (x-Derivative)

Table 3 can be derived by differentiation of Table 2 with x-coordinate (refer Appendix : Table of Differentiation). In the following, the notation is matched with Tables in Okada (1992).

$$\text{Displacement : } u^0(x, y, z) = \frac{M_0}{2\pi\mu} [u^0_A(x, y, z) - u^0_A(x, y, -z) + u^0_B(x, y, z) + zu^0_C(x, y, z)]$$

$$\text{x-Derivative : } \frac{\partial u^0}{\partial x}(x, y, z) = \frac{M_0}{2\pi\mu} \left[\frac{\partial u^0_A}{\partial x}(x, y, z) - \frac{\partial u^0_A}{\partial x}(x, y, -z) + \frac{\partial u^0_B}{\partial x}(x, y, z) + z \frac{\partial u^0_C}{\partial x}(x, y, z) \right]$$

(1) Strike slip

$$u_A^0 = \begin{pmatrix} \frac{1-\alpha}{2} \frac{q}{R^3} + \frac{\alpha}{2} \frac{3x^2q}{R^5} \\ \frac{1-\alpha}{2} \frac{x}{R^3} \sin\delta + \frac{\alpha}{2} \frac{3xyq}{R^5} \\ -\frac{1-\alpha}{2} \frac{x}{R^3} \cos\delta + \frac{\alpha}{2} \frac{3xdq}{R^5} \end{pmatrix} \quad u_B^0 = \begin{pmatrix} -\frac{3x^2q}{R^5} - \frac{1-\alpha}{\alpha} I_1^0 \sin\delta \\ -\frac{3xyq}{R^5} - \frac{1-\alpha}{\alpha} I_2^0 \sin\delta \\ -\frac{3cxq}{R^5} - \frac{1-\alpha}{\alpha} I_4^0 \sin\delta \end{pmatrix} \quad u_C^0 = \begin{pmatrix} -(1-\alpha) \frac{A_3}{R^3} \cos\delta + \alpha \frac{3cq}{R^5} A_5 \\ (1-\alpha) \frac{3xy}{R^5} \cos\delta + \alpha \frac{3cx}{R^5} \left(\sin\delta - \frac{5yq}{R^2} \right) \\ -(1-\alpha) \frac{3xy}{R^5} \sin\delta + \alpha \frac{3cx}{R^5} \left(\cos\delta + \frac{5dq}{R^2} \right) \end{pmatrix}$$

where, $d = c - z$, $q = y \sin\delta - d \cos\delta$, $R^2 = x^2 + y^2 + d^2$ and

$$I_1^0 = y \left[\frac{1}{R(R+d)^2} - x^2 \frac{3R+d}{R^3(R+d)^3} \right] \quad I_2^0 = x \left[\frac{1}{R(R+d)^2} - y^2 \frac{3R+d}{R^3(R+d)^3} \right] \quad I_4^0 = -xy \frac{2R+d}{R^3(R+d)^2}$$

$$\frac{\partial u_A^0}{\partial x} = \begin{pmatrix} -\frac{1-\alpha}{2} \frac{3xq}{R^5} + \frac{\alpha}{2} \frac{3xq}{R^5} (1+A_5) \\ \frac{1-\alpha}{2} \frac{A_3}{R^3} \sin\delta + \frac{\alpha}{2} \frac{3yq}{R^5} A_5 \\ -\frac{1-\alpha}{2} \frac{A_3}{R^3} \cos\delta + \frac{\alpha}{2} \frac{3dq}{R^5} A_5 \end{pmatrix} \quad \frac{\partial u_B^0}{\partial x} = \begin{pmatrix} -\frac{3xq}{R^5} (1+A_5) - \frac{1-\alpha}{\alpha} J_1^0 \sin\delta \\ -\frac{3yq}{R^5} A_5 - \frac{1-\alpha}{\alpha} J_2^0 \sin\delta \\ -\frac{3cq}{R^5} A_5 - \frac{1-\alpha}{\alpha} K_1^0 \sin\delta \end{pmatrix} \quad \begin{matrix} A_3 = 1 - \frac{3x^2}{R^2} \\ A_5 = 1 - \frac{5x^2}{R^2} \\ A_7 = 1 - \frac{7x^2}{R^2} \end{matrix}$$

$$\frac{\partial u_C^0}{\partial x} = \begin{pmatrix} (1-\alpha) \frac{3x}{R^5} (2+A_5) \cos\delta - \alpha \frac{15cxq}{R^7} (2+A_7) \\ (1-\alpha) \frac{3y}{R^5} A_5 \cos\delta + \alpha \frac{3c}{R^5} \left(A_5 \sin\delta - \frac{5yq}{R^2} A_7 \right) \\ -(1-\alpha) \frac{3y}{R^5} A_5 \sin\delta + \alpha \frac{3c}{R^5} \left(A_5 \cos\delta + \frac{5dq}{R^2} A_7 \right) \end{pmatrix} \quad \begin{matrix} J_1^0 \equiv \frac{\partial}{\partial x} I_1^0 = -3xy \left[\frac{3R+d}{R^3(R+d)^3} - x^2 \frac{5R^2+4Rd+d^2}{R^5(R+d)^4} \right] \\ J_2^0 \equiv \frac{\partial}{\partial x} I_2^0 = \frac{1}{R^3} - \frac{3}{R(R+d)^2} + 3x^2y^2 \frac{5R^2+4Rd+d^2}{R^5(R+d)^4} \\ K_1^0 \equiv \frac{\partial}{\partial x} I_4^0 = -y \left[\frac{2R+d}{R^3(R+d)^2} - x^2 \frac{8R^2+9Rd+3d^2}{R^5(R+d)^3} \right] \end{matrix}$$

The above three vectors correspond to the contents of the row of Strike-Slip in Table 3.

(2) Dip slip

$$u_A^0 = \begin{pmatrix} \frac{\alpha}{2} \frac{3xpq}{R^5} \\ \frac{1-\alpha}{2} \frac{s}{R^3} + \frac{\alpha}{2} \frac{3ypq}{R^5} \\ -\frac{1-\alpha}{2} \frac{t}{R^3} + \frac{\alpha}{2} \frac{3dpq}{R^5} \end{pmatrix} \quad u_B^0 = \begin{pmatrix} -\frac{3xpq}{R^5} + \frac{1-\alpha}{\alpha} I_3^0 \sin\delta \cos\delta \\ -\frac{3ypq}{R^5} + \frac{1-\alpha}{\alpha} I_1^0 \sin\delta \cos\delta \\ -\frac{3cpq}{R^5} + \frac{1-\alpha}{\alpha} I_5^0 \sin\delta \cos\delta \end{pmatrix} \quad u_C^0 = \begin{pmatrix} (1-\alpha) \frac{3xt}{R^5} - \alpha \frac{15cxpq}{R^7} \\ (1-\alpha) \left(\frac{3yt}{R^5} - \frac{\cos 2\delta}{R^3} \right) - \alpha \frac{15cypq}{R^7} + \alpha \frac{3cs}{R^5} \\ -(1-\alpha) \frac{A_3}{R^3} \sin\delta \cos\delta + \alpha \frac{15cdpq}{R^7} + \alpha \frac{3ct}{R^5} \end{pmatrix}$$

where, $d = c - z$, $\begin{cases} p = y \cos\delta + d \sin\delta \\ q = y \sin\delta - d \cos\delta \end{cases}$, $\begin{cases} s = p \sin\delta + q \cos\delta = y \sin 2\delta - d \cos 2\delta \\ t = p \cos\delta - q \sin\delta = y \cos 2\delta + d \sin 2\delta \end{cases}$ and

$$I_1^0 = y \left[\frac{1}{R(R+d)^2} - x^2 \frac{3R+d}{R^3(R+d)^3} \right] \quad I_2^0 = x \left[\frac{1}{R(R+d)^2} - y^2 \frac{3R+d}{R^3(R+d)^3} \right] \quad I_3^0 = \frac{x}{R^3} - I_2^0 \quad I_5^0 = \frac{1}{R(R+d)} - x^2 \frac{2R+d}{R^3(R+d)^2}$$

$$\frac{\partial u_A^0}{\partial x} = \begin{pmatrix} \frac{\alpha}{2} \frac{3pq}{R^5} A_5 \\ -\frac{1-\alpha}{2} \frac{3xs}{R^5} - \frac{\alpha}{2} \frac{15xypq}{R^7} \\ \frac{1-\alpha}{2} \frac{3xt}{R^5} + \frac{\alpha}{2} \frac{15xdpq}{R^7} \end{pmatrix} \quad \frac{\partial u_B^0}{\partial x} = \begin{pmatrix} -\frac{3pq}{R^5} A_5 + \frac{1-\alpha}{\alpha} J_3^0 \sin\delta \cos\delta \\ \frac{15xypq}{R^7} + \frac{1-\alpha}{\alpha} J_1^0 \sin\delta \cos\delta \\ \frac{15cxpq}{R^7} + \frac{1-\alpha}{\alpha} K_3^0 \sin\delta \cos\delta \end{pmatrix}$$

$$\frac{\partial u_C^0}{\partial x} = \begin{pmatrix} (1-\alpha) \frac{3t}{R^5} A_5 & -\alpha \frac{15cpq}{R^7} A_7 \\ (1-\alpha) \frac{3x}{R^5} \left(\cos 2\delta - \frac{5yt}{R^2} \right) & -\alpha \frac{15cx}{R^7} \left(s - \frac{7ypq}{R^2} \right) \\ (1-\alpha) \frac{3x}{R^5} (2 + A_5) \sin \delta \cos \delta & -\alpha \frac{15cx}{R^7} \left(t + \frac{7dpq}{R^2} \right) \end{pmatrix}$$

$$J_1^0 \equiv \frac{\partial}{\partial x} I_1^0 = -3xy \left[\frac{3R+d}{R^3(R+d)^3} - x^2 \frac{5R^2+4Rd+d^2}{R^5(R+d)^4} \right]$$

$$J_2^0 \equiv \frac{\partial}{\partial x} I_2^0 = \frac{1}{R^3} - \frac{3}{R(R+d)^2} + 3x^2 y^2 \frac{5R^2+4Rd+d^2}{R^5(R+d)^4}$$

$$J_3^0 \equiv \frac{\partial}{\partial x} I_3^0 = \frac{A_3}{R^3} - J_2^0$$

$$K_3^0 \equiv \frac{\partial}{\partial x} I_5^0 = -3x \frac{2R+d}{R^3(R+d)^2} + x^3 \frac{8R^2+9Rd+3d^2}{R^5(R+d)^3}$$

The above three vectors correspond to the contents of the row of Dip-Slip in Table 3.

(3) Tensile

$$u_A^0 = \begin{pmatrix} \frac{1-\alpha x}{2} \frac{x}{R^3} - \frac{\alpha 3xq^2}{2} \frac{1}{R^5} \\ \frac{1-\alpha t}{2} \frac{x}{R^3} - \frac{\alpha 3yq^2}{2} \frac{1}{R^5} \\ \frac{1-\alpha s}{2} \frac{x}{R^3} - \frac{\alpha 3dq^2}{2} \frac{1}{R^5} \end{pmatrix} \quad u_B^0 = \begin{pmatrix} \frac{3xq^2}{R^5} - \frac{1-\alpha}{\alpha} I_3^0 \sin^2 \delta \\ \frac{3yq^2}{R^5} - \frac{1-\alpha}{\alpha} I_1^0 \sin^2 \delta \\ \frac{3cq^2}{R^5} - \frac{1-\alpha}{\alpha} I_5^0 \sin^2 \delta \end{pmatrix}$$

$$u_C^0 = \begin{pmatrix} -(1-\alpha) \frac{3xs}{R^5} & +\alpha \frac{15cxq^2}{R^7} - \alpha \frac{3xz}{R^5} \\ (1-\alpha) \left(\frac{\sin 2\delta}{R^3} - \frac{3ys}{R^5} \right) & +3c\alpha \frac{t-y}{R^5} + \alpha \frac{15cyq^2}{R^7} - \alpha \frac{3yz}{R^5} \\ -(1-\alpha) \left(\frac{\cos^2 \delta}{R^3} + \frac{3x^2}{R^5} \sin^2 \delta \right) & -3c\alpha \frac{s-d}{R^5} - \alpha \frac{15cdq^2}{R^7} + \alpha \frac{3dz}{R^5} \end{pmatrix}$$

$$\frac{\partial u_A^0}{\partial x} = \begin{pmatrix} \frac{1-\alpha A_3}{2} \frac{x}{R^3} - \frac{\alpha 3q^2}{2} \frac{1}{R^5} A_5 \\ -\frac{1-\alpha 3xt}{2} \frac{x}{R^5} + \frac{\alpha 15xyq^2}{2} \frac{1}{R^7} \\ -\frac{1-\alpha 3xs}{2} \frac{x}{R^5} + \frac{\alpha 15xdq^2}{2} \frac{1}{R^7} \end{pmatrix} \quad \frac{\partial u_B^0}{\partial x} = \begin{pmatrix} \frac{3q^2}{R^5} A_5 - \frac{1-\alpha}{\alpha} J_3^0 \sin^2 \delta \\ -\frac{15xyq^2}{R^7} - \frac{1-\alpha}{\alpha} J_1^0 \sin^2 \delta \\ -\frac{15cxq^2}{R^7} - \frac{1-\alpha}{\alpha} K_3^0 \sin^2 \delta \end{pmatrix} \quad \begin{aligned} A_3 &= 1 - \frac{3x^2}{R^2} \\ A_5 &= 1 - \frac{5x^2}{R^2} \\ A_7 &= 1 - \frac{7x^2}{R^2} \end{aligned}$$

$$\frac{\partial u_C^0}{\partial x} = \begin{pmatrix} -(1-\alpha) \frac{3s}{R^5} A_5 & +\alpha \frac{15cq^2}{R^7} A_7 & -\alpha \frac{3z}{R^5} A_5 \\ -(1-\alpha) \frac{3x}{R^5} \left(\sin 2\delta - \frac{5ys}{R^2} \right) & -\alpha \frac{15cx}{R^7} \left(t-y + \frac{7yq^2}{R^2} \right) + \alpha \frac{15xyz}{R^7} \\ (1-\alpha) \frac{3x}{R^5} (\cos 2\delta - A_5 \sin^2 \delta) + \alpha \frac{15cx}{R^7} \left(s-d + \frac{7dq^2}{R^2} \right) & -\alpha \frac{15xdz}{R^7} \end{pmatrix}$$

Here, $\cos 2\delta - A_5 \sin^2 \delta = 1 - (2 + A_5) \sin^2 \delta$

The above three vectors correspond to the contents of the row of Tensile in Table 3.

(4) Inflation

$$u_A^0 = \begin{pmatrix} -\frac{1-\alpha x}{2} \frac{x}{R^3} \\ -\frac{1-\alpha y}{2} \frac{x}{R^3} \\ -\frac{1-\alpha d}{2} \frac{x}{R^3} \end{pmatrix} \quad u_B^0 = \begin{pmatrix} \frac{1-\alpha x}{\alpha} \frac{x}{R^3} \\ \frac{1-\alpha y}{\alpha} \frac{x}{R^3} \\ \frac{1-\alpha d}{\alpha} \frac{x}{R^3} \end{pmatrix} \quad u_C^0 = \begin{pmatrix} (1-\alpha) \frac{3xd}{R^5} \\ (1-\alpha) \frac{3yd}{R^5} \\ (1-\alpha) \frac{C_3}{R^3} \end{pmatrix} \quad C_3 = 1 - \frac{3d^2}{R^2}$$

$$\frac{\partial u_A^0}{\partial x} = \begin{pmatrix} -\frac{1-\alpha A_3}{2} \frac{x}{R^3} \\ \frac{1-\alpha 3xy}{2} \frac{x}{R^5} \\ \frac{1-\alpha 3xd}{2} \frac{x}{R^5} \end{pmatrix} \quad \frac{\partial u_B^0}{\partial x} = \begin{pmatrix} \frac{1-\alpha A_3}{\alpha} \frac{x}{R^3} \\ -\frac{1-\alpha 3xy}{\alpha} \frac{x}{R^5} \\ -\frac{1-\alpha 3xd}{\alpha} \frac{x}{R^5} \end{pmatrix} \quad \frac{\partial u_C^0}{\partial x} = \begin{pmatrix} (1-\alpha) \frac{3d}{R^5} A_5 \\ -(1-\alpha) \frac{15xyd}{R^7} \\ -(1-\alpha) \frac{3x}{R^5} C_5 \end{pmatrix} \quad \begin{aligned} A_3 &= 1 - \frac{3x^2}{R^2} \\ A_5 &= 1 - \frac{5x^2}{R^2} \\ C_5 &= 1 - \frac{5d^2}{R^2} \end{aligned}$$

The above three vectors correspond to the contents of the row of Inflation in Table 3.

[II] Derivation of Table 4 (y-Derivative)

Table 4 can be derived by differentiation of Table 2 with y-coordinate (refer Appendix : Table of Differentiation). In the following, the notation is matched with Tables in Okada (1992).

$$\text{Displacement : } u^0(x, y, z) = \frac{M_0}{2\pi\mu} [u^0_A(x, y, z) - u^0_A(x, y, -z) + u^0_B(x, y, z) + zu^0_C(x, y, z)]$$

$$\text{y-Derivative : } \frac{\partial u^0}{\partial y}(x, y, z) = \frac{M_0}{2\pi\mu} \left[\frac{\partial u^0_A}{\partial y}(x, y, z) - \frac{\partial u^0_A}{\partial y}(x, y, -z) + \frac{\partial u^0_B}{\partial y}(x, y, z) + z \frac{\partial u^0_C}{\partial y}(x, y, z) \right]$$

(1) Strike slip

$$u_A^0 = \begin{pmatrix} \frac{1-\alpha}{2} \frac{q}{R^3} + \frac{\alpha}{2} \frac{3x^2q}{R^5} \\ \frac{1-\alpha}{2} \frac{x}{R^3} \sin\delta + \frac{\alpha}{2} \frac{3xyq}{R^5} \\ -\frac{1-\alpha}{2} \frac{x}{R^3} \cos\delta + \frac{\alpha}{2} \frac{3xdq}{R^5} \end{pmatrix} \quad u_B^0 = \begin{pmatrix} -\frac{3x^2q}{R^5} - \frac{1-\alpha}{\alpha} I_1^0 \sin\delta \\ -\frac{3xyq}{R^5} - \frac{1-\alpha}{\alpha} I_2^0 \sin\delta \\ -\frac{3cxq}{R^5} - \frac{1-\alpha}{\alpha} I_4^0 \sin\delta \end{pmatrix} \quad u_C^0 = \begin{pmatrix} -(1-\alpha) \frac{A_3}{R^3} \cos\delta + \alpha \frac{3cq}{R^5} A_5 \\ (1-\alpha) \frac{3xy}{R^5} \cos\delta + \alpha \frac{3cx}{R^5} \left(\sin\delta - \frac{5yq}{R^2} \right) \\ -(1-\alpha) \frac{3xy}{R^5} \sin\delta + \alpha \frac{3cx}{R^5} \left(\cos\delta + \frac{5dq}{R^2} \right) \end{pmatrix}$$

where, $d = c - z$, $q = y \sin\delta - d \cos\delta$, $R^2 = x^2 + y^2 + d^2$ and

$$I_1^0 = y \left[\frac{1}{R(R+d)^2} - x^2 \frac{3R+d}{R^3(R+d)^3} \right] \quad I_2^0 = x \left[\frac{1}{R(R+d)^2} - y^2 \frac{3R+d}{R^3(R+d)^3} \right] \quad I_4^0 = -xy \frac{2R+d}{R^3(R+d)^2}$$

$$\frac{\partial u_A^0}{\partial y} = \begin{pmatrix} \frac{1-\alpha}{2} \frac{1}{R^3} \left(\sin\delta - \frac{3yq}{R^2} \right) + \frac{\alpha}{2} \frac{3x^2}{R^5} U \\ -\frac{1-\alpha}{2} \frac{3xy}{R^5} \sin\delta + \frac{\alpha}{2} \left(\frac{3xy}{R^5} U + \frac{3xq}{R^5} \right) \\ \frac{1-\alpha}{2} \frac{3xy}{R^5} \cos\delta + \frac{\alpha}{2} \frac{3xd}{R^5} U \end{pmatrix} \quad \frac{\partial u_B^0}{\partial y} = \begin{pmatrix} -\frac{3x^2}{R^5} U - \frac{1-\alpha}{\alpha} J_2^0 \sin\delta \\ -\frac{3xy}{R^5} U - \frac{3xq}{R^5} - \frac{1-\alpha}{\alpha} J_4^0 \sin\delta \\ -\frac{3cx}{R^5} U - \frac{1-\alpha}{\alpha} K_2^0 \sin\delta \end{pmatrix} \quad U = \sin\delta - \frac{5yq}{R^2}$$

$$\frac{\partial u_C^0}{\partial y} = \begin{pmatrix} (1-\alpha) \frac{3y}{R^5} A_5 \cos\delta + \alpha \frac{3c}{R^5} \left(A_5 \sin\delta - \frac{5yq}{R^2} A_7 \right) \\ (1-\alpha) \frac{3x}{R^5} B_5 \cos\delta - \alpha \frac{15cx}{R^7} (2y \sin\delta + q B_7) \\ -(1-\alpha) \frac{3x}{R^5} B_5 \sin\delta + \alpha \frac{15cx}{R^7} \left(d \sin\delta - y \cos\delta - \frac{7y dq}{R^2} \right) \end{pmatrix} \quad \begin{aligned} J_2^0 &\equiv \frac{\partial}{\partial y} I_1^0 = \frac{1}{R^3} - \frac{3}{R(R+d)^2} + 3x^2 y^2 \frac{5R^2 + 4Rd + d^2}{R^5(R+d)^4} \\ J_4^0 &\equiv \frac{\partial}{\partial y} I_2^0 = -3xy \left[\frac{3R+d}{R^3(R+d)^3} - y^2 \frac{5R^2 + 4Rd + d^2}{R^5(R+d)^4} \right] \\ K_2^0 &\equiv \frac{\partial}{\partial y} I_4^0 = -x \left[\frac{2R+d}{R^3(R+d)^2} - y^2 \frac{8R^2 + 9Rd + 3d^2}{R^5(R+d)^3} \right] \end{aligned}$$

Here, $d \sin\delta - y \cos\delta - \frac{7y dq}{R^2} = d \sin\delta - y \cos\delta - \frac{7y d}{R^2} (y \sin\delta - d \cos\delta) = d \left(1 - \frac{7y^2}{R^2} \right) \sin\delta - y \left(1 - \frac{7d^2}{R^2} \right) \cos\delta = dB_7 \sin\delta - yC_7 \cos\delta$

The above three vectors correspond to the contents of the row of Strike-Slip in Table 4.

(2) Dip slip

$$u_A^0 = \begin{pmatrix} \frac{\alpha}{2} \frac{3xpq}{R^5} \\ \frac{1-\alpha}{2} \frac{s}{R^3} + \frac{\alpha}{2} \frac{3ypq}{R^5} \\ -\frac{1-\alpha}{2} \frac{t}{R^3} + \frac{\alpha}{2} \frac{3dpq}{R^5} \end{pmatrix} \quad u_B^0 = \begin{pmatrix} -\frac{3xpq}{R^5} + \frac{1-\alpha}{\alpha} I_3^0 \sin\delta \cos\delta \\ -\frac{3ypq}{R^5} + \frac{1-\alpha}{\alpha} I_1^0 \sin\delta \cos\delta \\ -\frac{3cpq}{R^5} + \frac{1-\alpha}{\alpha} I_5^0 \sin\delta \cos\delta \end{pmatrix} \quad u_C^0 = \begin{pmatrix} (1-\alpha) \frac{3xt}{R^5} - \alpha \frac{15cxpq}{R^7} \\ (1-\alpha) \left(\frac{3yt}{R^5} - \frac{\cos 2\delta}{R^3} \right) - \alpha \frac{15cypq}{R^7} + \alpha \frac{3cs}{R^5} \\ -(1-\alpha) \frac{A_3}{R^3} \sin\delta \cos\delta + \alpha \frac{15cdpq}{R^7} + \alpha \frac{3ct}{R^5} \end{pmatrix}$$

where, $d = c - z$, $\begin{cases} p = y \cos\delta + d \sin\delta \\ q = y \sin\delta - d \cos\delta \end{cases}$, $\begin{cases} s = p \sin\delta + q \cos\delta = y \sin 2\delta - d \cos 2\delta \\ t = p \cos\delta - q \sin\delta = y \cos 2\delta + d \sin 2\delta \end{cases}$ and

$$I_1^0 = y \left[\frac{1}{R(R+d)^2} - x^2 \frac{3R+d}{R^3(R+d)^3} \right] \quad I_2^0 = x \left[\frac{1}{R(R+d)^2} - y^2 \frac{3R+d}{R^3(R+d)^3} \right] \quad I_3^0 = \frac{x}{R^3} - I_2^0 \quad I_5^0 = \frac{1}{R(R+d)} - x^2 \frac{2R+d}{R^3(R+d)^2}$$

$$\frac{\partial u_A^0}{\partial y} = \begin{pmatrix} \frac{\alpha}{2} \frac{3x}{R^5} V \\ \frac{1-\alpha}{2} \frac{1}{R^3} \left(\sin 2\delta - \frac{3ys}{R^2} \right) + \frac{\alpha}{2} \left(\frac{3y}{R^5} V + \frac{3pq}{R^5} \right) \\ -\frac{1-\alpha}{2} \frac{1}{R^3} \left(\cos 2\delta - \frac{3yt}{R^2} \right) + \frac{\alpha}{2} \frac{3d}{R^5} V \end{pmatrix} \quad \frac{\partial u_B^0}{\partial y} = \begin{pmatrix} -\frac{3x}{R^5} V + \frac{1-\alpha}{\alpha} J_1^0 \sin\delta \cos\delta \\ -\frac{3y}{R^5} V - \frac{3pq}{R^5} + \frac{1-\alpha}{\alpha} J_2^0 \sin\delta \cos\delta \\ -\frac{3c}{R^5} V + \frac{1-\alpha}{\alpha} K_1^0 \sin\delta \cos\delta \end{pmatrix} \quad V = s - \frac{5y pq}{R^2}$$

$$\frac{\partial u_c^o}{\partial y} = \begin{pmatrix} (1-\alpha) \frac{3x}{R^5} \left(\cos 2\delta - \frac{5yt}{R^2} \right) - \alpha \frac{15cx}{R^7} \left(s - \frac{7ypq}{R^2} \right) \\ (1-\alpha) \frac{3}{R^5} (2y \cos 2\delta + tB_5) + \alpha \frac{3c}{R^5} \left(\sin 2\delta - \frac{10ys}{R^2} - \frac{5pq}{R^2} B_7 \right) \\ (1-\alpha) \frac{3y}{R^5} A_5 \sin \delta \cos \delta - \alpha \frac{3c}{R^5} \left(-\cos 2\delta + \frac{5(yt-ds)}{R^2} + \frac{35ydpq}{R^4} \right) \end{pmatrix}$$

$$\text{Here, } \frac{5(yt-ds)}{R^2} = \frac{5(y^2+d^2)}{R^2} \cos 2\delta = \frac{5(R^2-x^2)}{R^2} \cos 2\delta = (4 + A_5) \cos 2\delta$$

The above three vectors correspond to the contents of the row of Dip-Slip in Table 4.

(3) Tensile

$$u_A^o = \begin{pmatrix} \frac{1-\alpha}{2} \frac{x}{R^3} - \frac{\alpha}{2} \frac{3xq^2}{R^5} \\ \frac{1-\alpha}{2} \frac{t}{R^3} - \frac{\alpha}{2} \frac{3yq^2}{R^5} \\ \frac{1-\alpha}{2} \frac{s}{R^3} - \frac{\alpha}{2} \frac{3dq^2}{R^5} \end{pmatrix} \quad u_B^o = \begin{pmatrix} \frac{3xq^2}{R^5} - \frac{1-\alpha}{\alpha} I_3^0 \sin^2 \delta \\ \frac{3yq^2}{R^5} - \frac{1-\alpha}{\alpha} I_1^0 \sin^2 \delta \\ \frac{3cq^2}{R^5} - \frac{1-\alpha}{\alpha} I_5^0 \sin^2 \delta \end{pmatrix}$$

$$u_C^o = \begin{pmatrix} -(1-\alpha) \frac{3xs}{R^5} & + \alpha \frac{15cxq^2}{R^7} - \alpha \frac{3xz}{R^5} \\ (1-\alpha) \left(\frac{\sin 2\delta}{R^3} - \frac{3ys}{R^5} \right) & + 3c\alpha \frac{t-y}{R^5} + \alpha \frac{15cyq^2}{R^7} - \alpha \frac{3yz}{R^5} \\ -(1-\alpha) \left(\frac{\cos^2 \delta}{R^3} + \frac{3x^2}{R^5} \sin^2 \delta \right) & - 3c\alpha \frac{s-d}{R^5} - \alpha \frac{15cdq^2}{R^7} + \alpha \frac{3dz}{R^5} \end{pmatrix}$$

$$\frac{\partial u_A^o}{\partial y} = \begin{pmatrix} -\frac{1-\alpha}{2} \frac{3xy}{R^5} & -\frac{\alpha}{2} \frac{3xq}{R^5} W \\ \frac{1-\alpha}{2} \frac{1}{R^3} \left(\cos 2\delta - \frac{3yt}{R^2} \right) - \frac{\alpha}{2} \left(\frac{3yq}{R^5} W + \frac{3q^2}{R^5} \right) & \frac{\partial u_B^o}{\partial y} = \begin{pmatrix} \frac{3xq}{R^5} W & -\frac{1-\alpha}{\alpha} J_1^0 \sin^2 \delta \\ \frac{3yq}{R^5} W + \frac{3q^2}{R^5} - \frac{1-\alpha}{\alpha} J_2^0 \sin^2 \delta \\ \frac{3cq}{R^5} W & -\frac{1-\alpha}{\alpha} K_1^0 \sin^2 \delta \end{pmatrix} \\ \frac{1-\alpha}{2} \frac{1}{R^3} \left(\sin 2\delta - \frac{3ys}{R^2} \right) - \frac{\alpha}{2} \frac{3dq}{R^5} W & \end{pmatrix} \quad W = 2\sin \delta - \frac{5yq}{R^2}$$

$$\frac{\partial u_C^o}{\partial y} = \begin{pmatrix} -(1-\alpha) \frac{3x}{R^5} \left(\sin 2\delta - \frac{5ys}{R^2} \right) & -\alpha \frac{15cx}{R^7} \left(-2q\sin \delta + \frac{7yq^2}{R^2} \right) & + \alpha \frac{15xyz}{R^7} \\ -(1-\alpha) \frac{3}{R^5} (2y \sin 2\delta + sB_5) - \alpha \frac{3c}{R^5} \left[2\sin^2 \delta + \frac{5y}{R^2} (t-y-2q\sin \delta) - \frac{5q^2}{R^2} B_7 \right] & - \alpha \frac{3z}{R^5} B_5 \\ (1-\alpha) \frac{3y}{R^5} (1 - A_5 \sin^2 \delta) & + \alpha \frac{3c}{R^5} \left[-\sin 2\delta + \frac{5(ys+dt)}{R^2} - \frac{5yd}{R^2} \left(2 - \frac{7q^2}{R^2} \right) \right] & - \alpha \frac{15ydz}{R^7} \end{pmatrix}$$

$$\text{Here, since } \begin{cases} y = p \cos \delta + q \sin \delta \\ t = p \cos \delta - q \sin \delta \end{cases}, \quad -2q \sin \delta = t - y$$

$$\text{and } \frac{5(ys+dt)}{R^2} = \frac{5(y^2+d^2)}{R^2} \sin 2\delta = \frac{5(R^2-x^2)}{R^2} \sin 2\delta = (4 + A_5) \sin 2\delta$$

The above three vectors correspond to the contents of the row of Tensile in Table 4.

(4) Inflation

$$u_A^o = \begin{pmatrix} -\frac{1-\alpha}{2} \frac{x}{R^3} \\ -\frac{1-\alpha}{2} \frac{y}{R^3} \\ -\frac{1-\alpha}{2} \frac{d}{R^3} \end{pmatrix} \quad u_B^o = \begin{pmatrix} \frac{1-\alpha}{\alpha} \frac{x}{R^3} \\ \frac{1-\alpha}{\alpha} \frac{y}{R^3} \\ \frac{1-\alpha}{\alpha} \frac{d}{R^3} \end{pmatrix} \quad u_C^o = \begin{pmatrix} (1-\alpha) \frac{3xd}{R^5} \\ (1-\alpha) \frac{3yd}{R^5} \\ (1-\alpha) \frac{C_3}{R^3} \end{pmatrix} \quad C_3 = 1 - \frac{3d^2}{R^2}$$

$$\frac{\partial u_A^o}{\partial y} = \begin{pmatrix} \frac{1-\alpha}{2} \frac{3xy}{R^5} \\ -\frac{1-\alpha}{2} \frac{B_3}{R^3} \\ \frac{1-\alpha}{2} \frac{3yd}{R^5} \end{pmatrix} \quad \frac{\partial u_B^o}{\partial y} = \begin{pmatrix} -\frac{1-\alpha}{\alpha} \frac{3xy}{R^5} \\ \frac{1-\alpha}{\alpha} \frac{B_3}{R^3} \\ -\frac{1-\alpha}{\alpha} \frac{3yd}{R^5} \end{pmatrix} \quad \frac{\partial u_C^o}{\partial y} = \begin{pmatrix} -(1-\alpha) \frac{15xyd}{R^7} \\ (1-\alpha) \frac{3d}{R^5} B_5 \\ -(1-\alpha) \frac{3y}{R^5} C_5 \end{pmatrix} \quad \begin{matrix} B_3 = 1 - \frac{3y^2}{R^2} \\ B_5 = 1 - \frac{5y^2}{R^2} \\ C_5 = 1 - \frac{5d^2}{R^2} \end{matrix}$$

The above three vectors correspond to the contents of the row of Inflation in Table 4.

[III] Derivation of Table 5 (z-Derivative)

Table 5 can be derived by differentiation of Table 2 with z-coordinate (refer Appendix : Table of Differentiation). In the following, the notation is matched with Tables in Okada (1992).

$$\text{Displacement : } u^0(x, y, z) = \frac{M_0}{2\pi\mu} [u^0_A(x, y, z) - u^0_A(x, y, -z) + u^0_B(x, y, z) + zu^0_C(x, y, z)]$$

$$\text{z-Derivative : } \frac{\partial u^0}{\partial z}(x, y, z) = \frac{M_0}{2\pi\mu} \left[\frac{\partial u^0_A}{\partial z}(x, y, z) + \frac{\partial u^0_A}{\partial z}(x, y, -z) + \frac{\partial u^0_B}{\partial z}(x, y, z) + u^0(x, y, z) + z \frac{\partial u^0_C}{\partial z}(x, y, z) \right]$$

(1) Strike slip

$$u^0_A = \begin{pmatrix} \frac{1-\alpha}{2} \frac{q}{R^3} + \frac{\alpha}{2} \frac{3x^2q}{R^5} \\ \frac{1-\alpha}{2} \frac{x}{R^3} \sin\delta + \frac{\alpha}{2} \frac{3xyq}{R^5} \\ -\frac{1-\alpha}{2} \frac{x}{R^3} \cos\delta + \frac{\alpha}{2} \frac{3xdq}{R^5} \end{pmatrix} \quad u^0_B = \begin{pmatrix} -\frac{3x^2q}{R^5} - \frac{1-\alpha}{\alpha} I_1^0 \sin\delta \\ -\frac{3xyq}{R^5} - \frac{1-\alpha}{\alpha} I_2^0 \sin\delta \\ -\frac{3cxq}{R^5} - \frac{1-\alpha}{\alpha} I_4^0 \sin\delta \end{pmatrix} \quad u^0_C = \begin{pmatrix} -(1-\alpha) \frac{A_3}{R^3} \cos\delta + \alpha \frac{3cq}{R^5} A_5 \\ (1-\alpha) \frac{3xy}{R^5} \cos\delta + \alpha \frac{3cx}{R^5} \left(\sin\delta - \frac{5yq}{R^2} \right) \\ -(1-\alpha) \frac{3xy}{R^5} \sin\delta + \alpha \frac{3cx}{R^5} \left(\cos\delta + \frac{5dq}{R^2} \right) \end{pmatrix}$$

where, $d = c - z$, $q = y \sin\delta - d \cos\delta$, $R^2 = x^2 + y^2 + d^2$ and

$$I_1^0 = y \left[\frac{1}{R(R+d)^2} - x^2 \frac{3R+d}{R^3(R+d)^3} \right] \quad I_2^0 = x \left[\frac{1}{R(R+d)^2} - y^2 \frac{3R+d}{R^3(R+d)^3} \right] \quad I_4^0 = -xy \frac{2R+d}{R^3(R+d)^2}$$

$$\frac{\partial u^0_A}{\partial z} = \begin{pmatrix} \frac{1-\alpha}{2} \frac{1}{R^3} \left(\cos\delta + \frac{3dq}{R^2} \right) + \frac{\alpha}{2} \frac{3x^2}{R^5} U' \\ \frac{1-\alpha}{2} \frac{3xd}{R^5} \sin\delta + \frac{\alpha}{2} \frac{3xy}{R^5} U' \\ -\frac{1-\alpha}{2} \frac{3xd}{R^5} \cos\delta + \frac{\alpha}{2} \left(\frac{3xd}{R^5} U' - \frac{3xq}{R^5} \right) \end{pmatrix} \quad \frac{\partial u^0_B}{\partial z} = \begin{pmatrix} -\frac{3x^2}{R^5} U' + \frac{1-\alpha}{\alpha} K_1^0 \sin\delta \\ -\frac{3xy}{R^5} U' + \frac{1-\alpha}{\alpha} K_2^0 \sin\delta \\ -\frac{3cx}{R^5} U' + \frac{1-\alpha}{\alpha} K_4^0 \sin\delta \end{pmatrix} \quad U' = \cos\delta + \frac{5dq}{R^2}$$

$$\frac{\partial u^0_C}{\partial z} = \begin{pmatrix} -(1-\alpha) \frac{3d}{R^5} A_5 \cos\delta + \alpha \frac{3c}{R^5} \left(A_5 \cos\delta + \frac{5dq}{R^2} A_7 \right) \\ (1-\alpha) \frac{15xyd}{R^7} \cos\delta + \alpha \frac{15cx}{R^7} \left(d \sin\delta - y \cos\delta - \frac{7y dq}{R^2} \right) \\ -(1-\alpha) \frac{15xyd}{R^7} \sin\delta + \alpha \frac{15cx}{R^7} (2d \cos\delta - q C_7) \end{pmatrix} \quad \begin{aligned} K_1^0 &\equiv -\frac{\partial}{\partial z} I_1^0 = -y \left[\frac{2R+d}{R^3(R+d)^2} - x^2 \frac{8R^2+9Rd+3d^2}{R^5(R+d)^3} \right] \\ K_2^0 &\equiv -\frac{\partial}{\partial z} I_2^0 = -x \left[\frac{2R+d}{R^3(R+d)^2} - y^2 \frac{8R^2+9Rd+3d^2}{R^5(R+d)^3} \right] \\ K_4^0 &\equiv -\frac{\partial}{\partial z} I_4^0 = \frac{3xy}{R^5} \end{aligned}$$

Here, $d \sin\delta - y \cos\delta - \frac{7y dq}{R^2} = d \sin\delta - y \cos\delta - \frac{7y d}{R^2} (y \sin\delta - d \cos\delta) = d \left(1 - \frac{7y^2}{R^2} \right) \sin\delta - y \left(1 - \frac{7d^2}{R^2} \right) \cos\delta = dB_7 \sin\delta - yC_7 \cos\delta$

The above three vectors correspond to the contents of the row of Strike-Slip in Table 5.

(2) Dip slip

$$u^0_A = \begin{pmatrix} \frac{\alpha}{2} \frac{3xpq}{R^5} \\ \frac{1-\alpha}{2} \frac{s}{R^3} + \frac{\alpha}{2} \frac{3ypq}{R^5} \\ -\frac{1-\alpha}{2} \frac{t}{R^3} + \frac{\alpha}{2} \frac{3dpq}{R^5} \end{pmatrix} \quad u^0_B = \begin{pmatrix} -\frac{3xpq}{R^5} + \frac{1-\alpha}{\alpha} I_3^0 \sin\delta \cos\delta \\ -\frac{3ypq}{R^5} + \frac{1-\alpha}{\alpha} I_1^0 \sin\delta \cos\delta \\ -\frac{3cpq}{R^5} + \frac{1-\alpha}{\alpha} I_5^0 \sin\delta \cos\delta \end{pmatrix} \quad u^0_C = \begin{pmatrix} (1-\alpha) \frac{3xt}{R^5} - \alpha \frac{15cxpq}{R^7} \\ (1-\alpha) \left(\frac{3yt}{R^5} - \frac{\cos 2\delta}{R^3} \right) - \alpha \frac{15cypq}{R^7} + \alpha \frac{3cs}{R^5} \\ -(1-\alpha) \frac{A_3}{R^3} \sin\delta \cos\delta + \alpha \frac{15cdpq}{R^7} + \alpha \frac{3ct}{R^5} \end{pmatrix}$$

where, $d = c - z$, $\begin{cases} p = y \cos\delta + d \sin\delta \\ q = y \sin\delta - d \cos\delta \end{cases}$, $\begin{cases} s = p \sin\delta + q \cos\delta = y \sin 2\delta - d \cos 2\delta \\ t = p \cos\delta - q \sin\delta = y \cos 2\delta + d \sin 2\delta \end{cases}$ and

$$I_1^0 = y \left[\frac{1}{R(R+d)^2} - x^2 \frac{3R+d}{R^3(R+d)^3} \right] \quad I_2^0 = x \left[\frac{1}{R(R+d)^2} - y^2 \frac{3R+d}{R^3(R+d)^3} \right] \quad I_3^0 = \frac{x}{R^3} - I_2^0 \quad I_5^0 = \frac{1}{R(R+d)} - x^2 \frac{2R+d}{R^3(R+d)^2}$$

$$\frac{\partial u^0_A}{\partial z} = \begin{pmatrix} \frac{\alpha}{2} \frac{3x}{R^5} V' \\ \frac{1-\alpha}{2} \frac{1}{R^3} \left(\cos 2\delta + \frac{3ds}{R^2} \right) + \frac{\alpha}{2} \frac{3y}{R^5} V' \\ \frac{1-\alpha}{2} \frac{1}{R^3} \left(\sin 2\delta - \frac{3dt}{R^2} \right) + \frac{\alpha}{2} \left(\frac{3d}{R^5} V' - \frac{3pq}{R^5} \right) \end{pmatrix} \quad V' = t + \frac{5dpq}{R^2}$$

$$\frac{\partial u^0_B}{\partial z} = \begin{pmatrix} -\frac{3x}{R^5} V' - \frac{1-\alpha}{\alpha} K_3^0 \sin\delta \cos\delta \\ -\frac{3y}{R^5} V' - \frac{1-\alpha}{\alpha} K_1^0 \sin\delta \cos\delta \\ -\frac{3c}{R^5} V' - \frac{1-\alpha}{\alpha} K_5^0 \sin\delta \cos\delta \end{pmatrix} \quad \begin{aligned} K_3^0 &\equiv -\frac{\partial}{\partial z} I_3^0 = -\frac{3xd}{R^5} - K_2^0 \\ K_1^0 &\equiv -\frac{\partial}{\partial z} I_1^0 = -y \left[\frac{2R+d}{R^3(R+d)^2} - x^2 \frac{8R^2+9Rd+3d^2}{R^5(R+d)^3} \right] \\ K_5^0 &\equiv -\frac{\partial}{\partial z} I_5^0 = -\frac{A_3}{R^3} \end{aligned}$$

$$\frac{\partial u_C^o}{\partial z} = \begin{pmatrix} -(1-\alpha) \frac{3x}{R^5} \left(\sin 2\delta - \frac{5dt}{R^2} \right) & -\alpha \frac{15cx}{R^7} \left(t + \frac{7dpq}{R^2} \right) \\ -(1-\alpha) \frac{3}{R^5} \left[y \sin 2\delta + d \cos 2\delta - \frac{5ydt}{R^2} \right] & -\alpha \frac{3c}{R^5} \left(-\cos 2\delta + \frac{5(yt-ds)}{R^2} + \frac{35ydpq}{R^4} \right) \\ -(1-\alpha) \frac{3d}{R^5} A_5 \sin \delta \cos \delta & -\alpha \frac{3c}{R^5} \left(\sin 2\delta - \frac{10dt}{R^2} + \frac{5pq}{R^2} C_7 \right) \end{pmatrix}$$

Here, $y \sin 2\delta + d \cos 2\delta - \frac{5ydt}{R^2} = y \sin 2\delta + d \cos 2\delta - \frac{5yd}{R^2} (y \cos 2\delta + d \sin 2\delta) = dB_5 \cos 2\delta + yC_5 \sin 2\delta$

and $\frac{5(yt-ds)}{R^2} = \frac{5(y^2+d^2)}{R^2} \cos 2\delta = \frac{5(R^2-x^2)}{R^2} \cos 2\delta = (4 + A_5) \cos 2\delta$

The above three vectors correspond to the contents of the row of Dip-Slip in Table 5.

(3) Tensile

$$u_A^o = \begin{pmatrix} \frac{1-\alpha x}{2 R^3} - \frac{\alpha 3xq^2}{2 R^5} \\ \frac{1-\alpha t}{2 R^3} - \frac{\alpha 3yq^2}{2 R^5} \\ \frac{1-\alpha s}{2 R^3} - \frac{\alpha 3dq^2}{2 R^5} \end{pmatrix} \quad u_B^o = \begin{pmatrix} \frac{3xq^2}{R^5} - \frac{1-\alpha}{\alpha} I_3^0 \sin^2 \delta \\ \frac{3yq^2}{R^5} - \frac{1-\alpha}{\alpha} I_1^0 \sin^2 \delta \\ \frac{3cq^2}{R^5} - \frac{1-\alpha}{\alpha} I_5^0 \sin^2 \delta \end{pmatrix}$$

$$u_C^o = \begin{pmatrix} -(1-\alpha) \frac{3xs}{R^5} & +\alpha \frac{15cxq^2}{R^7} - \alpha \frac{3xz}{R^5} \\ (1-\alpha) \left(\frac{\sin 2\delta}{R^3} - \frac{3ys}{R^5} \right) & +3c\alpha \frac{t-y}{R^5} + \alpha \frac{15cyq^2}{R^7} - \alpha \frac{3yz}{R^5} \\ -(1-\alpha) \left(\frac{\cos^2 \delta}{R^3} + \frac{3x^2}{R^5} \sin^2 \delta \right) & -3c\alpha \frac{s-d}{R^5} - \alpha \frac{15cdq^2}{R^7} + \alpha \frac{3dz}{R^5} \end{pmatrix}$$

$$\frac{\partial u_A^o}{\partial z} = \begin{pmatrix} \frac{1-\alpha 3xd}{2 R^5} & -\frac{\alpha 3xq}{2 R^5} W' \\ -\frac{1-\alpha}{2 R^3} \left(\sin 2\delta - \frac{3dt}{R^2} \right) & -\frac{\alpha 3yq}{2 R^5} W' \\ \frac{1-\alpha}{2 R^3} \left(\cos 2\delta + \frac{3ds}{R^2} \right) & -\frac{\alpha}{2} \left(\frac{3dq}{R^5} W' - \frac{3q^2}{R^5} \right) \end{pmatrix} \quad \frac{\partial u_B^o}{\partial z} = \begin{pmatrix} \frac{3xq}{R^5} W' + \frac{1-\alpha}{\alpha} K_3^0 \sin^2 \delta \\ \frac{3yq}{R^5} W' + \frac{1-\alpha}{\alpha} K_1^0 \sin^2 \delta \\ \frac{3cq}{R^5} W' + \frac{1-\alpha}{\alpha} K_5^0 \sin^2 \delta \end{pmatrix} \quad W' = 2 \cos \delta + \frac{5dq}{R^2}$$

$$\frac{\partial u_C^o}{\partial z} = \begin{pmatrix} -(1-\alpha) \frac{3x}{R^5} \left(\cos 2\delta + \frac{5ds}{R^2} \right) & +\alpha \frac{15cx}{R^7} \left(2q \cos \delta + \frac{7dq^2}{R^2} \right) - \alpha \frac{3x}{R^5} \left(1 + \frac{5dz}{R^2} \right) \\ (1-\alpha) \frac{3}{R^5} \left(d \sin 2\delta - y \cos 2\delta - \frac{5yds}{R^2} \right) + \alpha \frac{3c}{R^5} \left[-\sin 2\delta + \frac{5d(t-y)}{R^2} + \frac{5y}{R^2} \left(2q \cos \delta + \frac{7dq^2}{R^2} \right) \right] & -\alpha \frac{3y}{R^5} \left(1 + \frac{5dz}{R^2} \right) \\ -(1-\alpha) \frac{3d}{R^5} (1 - A_5 \sin^2 \delta) & -\alpha \frac{3c}{R^5} \left[1 + \cos 2\delta + \frac{5d(s-d)}{R^2} + \frac{5}{R^2} (2dq \cos \delta - q^2 C_7) \right] + \alpha \frac{3c}{R^5} - \alpha \frac{3z}{R^5} (1 + C_5) \end{pmatrix}$$

Here, $d \sin 2\delta - y \cos 2\delta - \frac{5yds}{R^2} = d \sin 2\delta - y \cos 2\delta - \frac{5yd}{R^2} (y \sin 2\delta - d \cos 2\delta) = dB_5 \sin 2\delta - yC_5 \cos 2\delta$

Since $\begin{cases} d = p \sin \delta - q \cos \delta \\ s = p \sin \delta + q \cos \delta \end{cases}$, $2q \cos \delta = s - d$

So, $\frac{5d(t-y)}{R^2} + \frac{5y}{R^2} \left(2q \cos \delta + \frac{7dq^2}{R^2} \right) = \frac{5(ys+dt)}{R^2} - \frac{5yd}{R^2} \left(2 - \frac{7q^2}{R^2} \right) = \frac{5(R^2-x^2)}{R^2} \sin 2\delta - \frac{5yd}{R^2} \left(2 - \frac{7q^2}{R^2} \right) = (4 + A_5) \sin 2\delta - \frac{5yd}{R^2} \left(2 - \frac{7q^2}{R^2} \right)$

The above three vectors correspond to the contents of the row of Tensile in Table 5.

(4) Inflation

$$u_A^o = \begin{pmatrix} -\frac{1-\alpha x}{2 R^3} \\ -\frac{1-\alpha y}{2 R^3} \\ -\frac{1-\alpha d}{2 R^3} \end{pmatrix} \quad u_B^o = \begin{pmatrix} \frac{1-\alpha x}{\alpha R^3} \\ \frac{1-\alpha y}{\alpha R^3} \\ \frac{1-\alpha d}{\alpha R^3} \end{pmatrix} \quad u_C^o = \begin{pmatrix} (1-\alpha) \frac{3xd}{R^5} \\ (1-\alpha) \frac{3yd}{R^5} \\ (1-\alpha) \frac{C_3}{R^3} \end{pmatrix}$$

$$\frac{\partial u_A^o}{\partial z} = \begin{pmatrix} -\frac{1-\alpha 3xd}{2 R^5} \\ -\frac{1-\alpha 3yd}{2 R^5} \\ \frac{1-\alpha C_3}{2 R^3} \end{pmatrix} \quad \frac{\partial u_B^o}{\partial z} = \begin{pmatrix} \frac{1-\alpha 3xd}{\alpha R^5} \\ \frac{1-\alpha 3yd}{\alpha R^5} \\ -\frac{1-\alpha C_3}{\alpha R^3} \end{pmatrix} \quad \frac{\partial u_C^o}{\partial z} = \begin{pmatrix} -(1-\alpha) \frac{3x}{R^5} C_5 \\ -(1-\alpha) \frac{3y}{R^5} C_5 \\ (1-\alpha) \frac{3d}{R^5} (2 + C_5) \end{pmatrix} \quad \begin{matrix} C_3 = 1 - \frac{3d^2}{R^2} \\ C_5 = 1 - \frac{5d^2}{R^2} \end{matrix}$$

The above three vectors correspond to the contents of the row of Inflation in Table 5.

Appendix : Table of Differentiation

$$R = \sqrt{x^2 + y^2 + d^2}, \quad d = c - z, \quad \begin{cases} p = y \cos \delta + d \sin \delta \\ q = y \sin \delta - d \cos \delta \end{cases}, \quad \begin{cases} s = p \sin \delta + q \cos \delta = y \sin 2\delta - d \cos 2\delta \\ t = p \cos \delta - q \sin \delta = y \cos 2\delta + d \sin 2\delta \end{cases}$$

f	$\partial f / \partial x$	$\partial f / \partial y$	$\partial f / \partial z = -\partial f / \partial d$
$1/R^3$	$-3x/R^5$	$-3y/R^5$	$3d/R^5$
x/R^3	A_3/R^3	$-3xy/R^5$	$3xd/R^5$
y/R^3	$-3xy/R^5$	B_3/R^3	$3yd/R^5$
d/R^3	$-3xd/R^5$	$-3yd/R^5$	$-C_3/R^3$
q/R^3	$-3xq/R^5$	$\frac{1}{R^3} \left(\sin \delta - \frac{3yq}{R^2} \right)$	$\frac{1}{R^3} \left(\cos \delta + \frac{3dq}{R^2} \right)$
s/R^3	$-3xs/R^5$	$\frac{1}{R^3} \left(\sin 2\delta - \frac{3ys}{R^2} \right)$	$\frac{1}{R^3} \left(\cos 2\delta + \frac{3ds}{R^2} \right)$
t/R^3	$-3xt/R^5$	$\frac{1}{R^3} \left(\cos 2\delta - \frac{3yt}{R^2} \right)$	$-\frac{1}{R^3} \left(\sin 2\delta - \frac{3dt}{R^2} \right)$
$\frac{A_3}{R^3} = \frac{1}{R^3} - \frac{3x^2}{R^5}$	$-\frac{3x}{R^5} (2 + A_5)$	$-\frac{3y}{R^5} A_5$	$\frac{3d}{R^5} A_5$
$1/R^5$	$-5x/R^7$	$-5y/R^7$	$5d/R^7$
x/R^5	A_5/R^5	$-5xy/R^7$	$5xd/R^7$
y/R^5	$-5xy/R^7$	B_5/R^5	$5yd/R^7$
d/R^5	$-5xd/R^7$	$-5yd/R^7$	$-C_5/R^5$
q/R^5	$-5xq/R^7$	$\frac{1}{R^5} \left(\sin \delta - \frac{5yq}{R^2} \right) = \frac{U}{R^5}$	$\frac{1}{R^5} \left(\cos \delta + \frac{5dq}{R^2} \right) = \frac{U'}{R^5}$
s/R^5	$-5xs/R^7$	$\frac{1}{R^5} \left(\sin 2\delta - \frac{5ys}{R^2} \right)$	$\frac{1}{R^5} \left(\cos 2\delta + \frac{5ds}{R^2} \right)$
t/R^5	$-5xt/R^7$	$\frac{1}{R^5} \left(\cos 2\delta - \frac{5yt}{R^2} \right)$	$-\frac{1}{R^5} \left(\sin 2\delta - \frac{5dt}{R^2} \right)$
x^2/R^5	$\frac{x}{R^5} (1 + A_5)$	$-5x^2y/R^7$	$5x^2d/R^7$
y^2/R^5	$-5xy^2/R^7$	$\frac{y}{R^5} (1 + B_5)$	$5y^2d/R^7$
d^2/R^5	$-5xd^2/R^7$	$-5yd^2/R^7$	$-\frac{d}{R^5} (1 + C_5)$
xy/R^5	$\frac{y}{R^5} A_5$	$\frac{x}{R^5} B_5$	$5xyd/R^7$
xd/R^5	$\frac{d}{R^5} A_5$	$-5xyd/R^7$	$-\frac{x}{R^5} C_5$
yd/R^5	$-5xyd/R^7$	$\frac{d}{R^5} B_5$	$-\frac{x}{R^5} C_5$
xq/R^5	$\frac{q}{R^5} A_5$	$\frac{x}{R^5} \left(\sin \delta - \frac{5yq}{R^2} \right) = \frac{x}{R^5} U$	$\frac{x}{R^5} \left(\cos \delta + \frac{5dq}{R^2} \right) = \frac{x}{R^5} U'$
pq/R^5	$-5xpq/R^7$	$\frac{1}{R^5} \left(s - \frac{5ypq}{R^2} \right) = \frac{V}{R^5}$	$\frac{1}{R^5} \left(t + \frac{5dpq}{R^2} \right) = \frac{V'}{R^5}$
q^2/R^5	$-5xq^2/R^7$	$\frac{q}{R^5} \left(2\sin \delta - \frac{5yq}{R^2} \right) = \frac{q}{R^5} W$	$\frac{q}{R^5} \left(2\cos \delta + \frac{5dq}{R^2} \right) = \frac{q}{R^5} W'$
xs/R^5	$\frac{s}{R^5} A_5$	$\frac{x}{R^5} \left(\sin 2\delta - \frac{5ys}{R^2} \right)$	$\frac{x}{R^5} \left(\cos 2\delta + \frac{5ds}{R^2} \right)$
xt/R^5	$\frac{t}{R^5} A_5$	$\frac{x}{R^5} \left(\cos 2\delta - \frac{5yt}{R^2} \right)$	$-\frac{x}{R^5} \left(\sin 2\delta - \frac{5dt}{R^2} \right)$
ys/R^5	$-5xys/R^7$	$\frac{1}{R^5} (y \sin 2\delta + s B_5)$	$\frac{y}{R^5} \left(\cos 2\delta + \frac{5ds}{R^2} \right)$
yt/R^5	$-5xyt/R^7$	$\frac{1}{R^5} (y \cos 2\delta + t B_5)$	$-\frac{y}{R^5} \left(\sin 2\delta - \frac{5dt}{R^2} \right)$
xz/R^5	$\frac{z}{R^5} A_5$	$-5xyz/R^7$	$\frac{x}{R^5} \left(1 + \frac{5dz}{R^2} \right)$
yz/R^5	$-5xyz/R^7$	$\frac{z}{R^5} B_5$	$\frac{y}{R^5} \left(1 + \frac{5dz}{R^2} \right)$
dz/R^5	$-5xdz/R^7$	$-5ydz/R^7$	$\frac{1}{R^5} (d - z C_5)$

f	$\partial f/\partial x$	$\partial f/\partial y$	$\partial f/\partial z = -\partial f/\partial d$
x^2q/R^5	$\frac{xq}{R^5}(1 + A_5)$	$\frac{x^2}{R^5}\left(\sin\delta - \frac{5yq}{R^2}\right) = \frac{x^2}{R^5}U$	$\frac{x^2}{R^5}\left(\cos\delta + \frac{5dq}{R^2}\right) = \frac{x^2}{R^5}U'$
xyq/R^5	$\frac{yq}{R^5}A_5$	$\frac{x}{R^5}(y\sin\delta + qB_5) = \frac{xy}{R^5}U + \frac{xq}{R^5}$	$\frac{xy}{R^5}\left(\cos\delta + \frac{5dq}{R^2}\right) = \frac{xy}{R^5}U'$
xdq/R^5	$\frac{dq}{R^5}A_5$	$\frac{xd}{R^5}\left(\sin\delta - \frac{5yq}{R^2}\right) = \frac{xd}{R^5}U$	$\frac{x}{R^5}(d\cos\delta - qC_5) = \frac{xd}{R^5}U' - \frac{xq}{R^5}$
xpq/R^5	$\frac{pq}{R^5}A_5$	$\frac{x}{R^5}\left(s - \frac{5ypq}{R^2}\right) = \frac{x}{R^5}V$	$\frac{x}{R^5}\left(t + \frac{5dpq}{R^2}\right) = \frac{x}{R^5}V'$
ypq/R^5	$-5xypq/R^7$	$\frac{1}{R^5}(ys + pqB_5) = \frac{y}{R^5}V + \frac{pq}{R^5}$	$\frac{y}{R^5}\left(t + \frac{5dpq}{R^2}\right) = \frac{y}{R^5}V'$
dpq/R^5	$-5xdpq/R^7$	$\frac{d}{R^5}\left(s - \frac{5ypq}{R^2}\right) = \frac{d}{R^5}V$	$\frac{1}{R^5}(dt - pqC_5) = \frac{d}{R^5}V' - \frac{pq}{R^5}$
xq^2/R^5	$\frac{q^2}{R^5}A_5$	$\frac{xq}{R^5}\left(2\sin\delta - \frac{5yq}{R^2}\right) = \frac{xq}{R^5}W$	$\frac{xq}{R^5}\left(2\cos\delta + \frac{5dq}{R^2}\right) = \frac{xq}{R^5}W'$
yq^2/R^5	$-5xyq^2/R^7$	$\frac{q}{R^5}(2y\sin\delta + qB_5) = \frac{yq}{R^5}W + \frac{q^2}{R^5}$	$\frac{yq}{R^5}\left(2\cos\delta + \frac{5dq}{R^2}\right) = \frac{yq}{R^5}W'$
dq^2/R^5	$-5xdq^2/R^7$	$\frac{dq}{R^5}\left(2\sin\delta - \frac{5yq}{R^2}\right) = \frac{xq}{R^5}W$	$\frac{q}{R^5}(2d\cos\delta - qC_5) = \frac{dq}{R^5}W' - \frac{q^2}{R^5}$
x^2q/R^7	$\frac{xq}{R^7}(1 + A_7)$	$\frac{x^2}{R^7}\left(\sin\delta - \frac{7yq}{R^2}\right)$	$\frac{x^2}{R^7}\left(\cos\delta + \frac{7dq}{R^2}\right)$
xyq/R^7	$\frac{yq}{R^7}A_7$	$\frac{x}{R^7}(y\sin\delta + qB_7)$	$\frac{xy}{R^7}\left(\cos\delta + \frac{7dq}{R^2}\right)$
xdq/R^7	$\frac{dq}{R^7}A_7$	$\frac{xd}{R^7}\left(\sin\delta - \frac{7yq}{R^2}\right)$	$\frac{x}{R^7}(d\cos\delta - qC_7)$
xpq/R^7	$\frac{pq}{R^7}A_7$	$\frac{x}{R^7}\left(s - \frac{7ypq}{R^2}\right)$	$\frac{x}{R^7}\left(t + \frac{7dpq}{R^2}\right)$
ypq/R^7	$-7xypq/R^9$	$\frac{1}{R^7}(ys + pqB_7)$	$\frac{y}{R^7}\left(t + \frac{7dpq}{R^2}\right)$
dpq/R^7	$-7xdpq/R^9$	$\frac{d}{R^7}\left(s - \frac{7ypq}{R^2}\right)$	$\frac{1}{R^7}(dt - pqC_7)$
xq^2/R^7	$\frac{q^2}{R^7}A_7$	$\frac{xq}{R^7}\left(2\sin\delta - \frac{7yq}{R^2}\right)$	$\frac{xq}{R^7}\left(2\cos\delta + \frac{7dq}{R^2}\right)$
yq^2/R^7	$-7xyq^2/R^9$	$\frac{q}{R^7}(2y\sin\delta + qB_7)$	$\frac{yq}{R^7}\left(2\cos\delta + \frac{7dq}{R^2}\right)$
dq^2/R^7	$-7xdq^2/R^9$	$\frac{dq}{R^7}\left(2\sin\delta - \frac{7yq}{R^2}\right)$	$\frac{q}{R^7}(2d\cos\delta - qC_7)$
$\frac{1}{R(R+d)}$	$-\frac{2R+d}{R^3(R+d)^2}$	$-\frac{2R+d}{R^3(R+d)^2}$	$\frac{1}{R^3}$
$\frac{1}{R(R+d)^2}$	$-\frac{3R+d}{R^3(R+d)^3}$	$-\frac{3R+d}{R^3(R+d)^3}$	$\frac{2R+d}{R^3(R+d)^2}$
$\frac{2R+d}{R^3(R+d)^2}$	$-\frac{8R^2+9Rd+3d^2}{R^5(R+d)^3}$	$-\frac{8R^2+9Rd+3d^2}{R^5(R+d)^3}$	$\frac{3}{R^5}$
$\frac{3R+d}{R^3(R+d)^3}$	$-\frac{5R^2+4Rd+d^2}{R^5(R+d)^4}$	$-\frac{5R^2+4Rd+d^2}{R^5(R+d)^4}$	$\frac{8R^2+9Rd+3d^2}{R^5(R+d)^3}$

$$\begin{array}{llll}
 A_3 = 1 - \frac{3x^2}{R^2} & B_3 = 1 - \frac{3y^2}{R^2} & C_3 = 1 - \frac{3d^2}{R^2} & U = \sin\delta - \frac{5yq}{R^2} & U' = \cos\delta + \frac{5dq}{R^2} \\
 A_5 = 1 - \frac{5x^2}{R^2} & B_5 = 1 - \frac{5y^2}{R^2} & C_5 = 1 - \frac{5d^2}{R^2} & V = s - \frac{5ypq}{R^2} & V' = t + \frac{5dpq}{R^2} \\
 A_7 = 1 - \frac{7x^2}{R^2} & B_7 = 1 - \frac{7y^2}{R^2} & C_7 = 1 - \frac{7d^2}{R^2} & W = 2\sin\delta - \frac{5yq}{R^2} & W' = 2\cos\delta + \frac{5dq}{R^2}
 \end{array}$$